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# A novel adaptive beamformers for MEG source reconstruction effective when large background brain activities exist

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# Interferences affecting to MEG sensor data

## Low-rank interference

# High-rank interference







**Electronics** 

Heartbeat

Dental & Jaw Muscles







no specific spatial, temporal, and frequency patterns

# Data model

$$\boldsymbol{b}(t) = \boldsymbol{b}_{S}(t) + \boldsymbol{b}_{I}(t) + \boldsymbol{n}(t)$$

Measured magnetic field

Sensor noise Background interference

$$\boldsymbol{b}(t) = \underline{\boldsymbol{b}_{\scriptscriptstyle S}(t) + \boldsymbol{b}_{\scriptscriptstyle I}'(t) + \boldsymbol{b}_{\scriptscriptstyle I}''(t) + \boldsymbol{n}(t)}$$

$$\uparrow$$

$$\boldsymbol{b}_{\scriptscriptstyle S}(t)$$

Signal magnetic field

### Definitions

Data covariance:  $\mathbf{R} = \langle \mathbf{b}(t)\mathbf{b}^{T}(t) \rangle$ Signal covariance:  $\mathbf{R}_{S} = \langle \mathbf{b}_{S}(t)\mathbf{b}_{S}^{T}(t) \rangle$ Interference plus noise covariance:  $\mathbf{R}_{i+n} = \langle (\mathbf{b}_{I}(t) + \mathbf{n}(t))(\mathbf{b}_{I}(t) + \mathbf{n}(t))^{T} \rangle$ 

## Data model

Task: 
$$\boldsymbol{b}(t) = \boldsymbol{b}_{S}(t) + \boldsymbol{b}_{I}(t) + \boldsymbol{n}(t)$$
  
Control:  $\boldsymbol{b}_{C}(t) = \boldsymbol{b}_{I}(t) + \boldsymbol{n}(t)$ 

**Covariance matrix relations** 

Task: 
$$\mathbf{R} = \mathbf{R}_S + \mathbf{R}_{i+n}$$
  
Control:  $\mathbf{R}_C = \mathbf{R}_{i+n}$ 

**Problem** How to obtain source reconstruction free from the influence of  $\boldsymbol{b}_I(t)$ 

We propose: (1)Prewhitening beamforming (2)Partitioned factor analysis + adaptive beamforming

## **Prewhitening estimation of signal covariance**

Calculate 
$$\tilde{\boldsymbol{R}} = \boldsymbol{R}_{C}^{-1/2} \boldsymbol{R} \boldsymbol{R}_{C}^{-1/2}$$

(Tilde is used to indicate the prewhitened version of a matrix)

$$\tilde{\mathbf{R}}_{S} = \sum_{j=1}^{Q} \gamma_{j} \mathbf{u}_{j} \mathbf{u}_{j}^{T} \implies \tilde{\mathbf{R}} = \sum_{j=1}^{Q} (\gamma_{j} + 1) \mathbf{u}_{j} \mathbf{u}_{j}^{T} + \sum_{j=Q+1}^{M} \mathbf{u}_{j} \mathbf{u}_{j}^{T}.$$

$$\widehat{\mathbf{R}} \text{ has signal-level eigenvalues greater than 1,}$$
and their eigenvectors are equal to those of  $\tilde{\mathbf{R}}$ 

Signal covariance estimation

For details, poster P-163, (session P4-1) 8/22 3:00-5:00PM

# **Prewhitening beamforming**

Signal covariance estimation

$$\hat{\boldsymbol{R}}_{S} = \boldsymbol{R}_{C}^{1/2} \left[ \sum_{j=1}^{Q} (\boldsymbol{\gamma}_{j} - 1) \boldsymbol{u}_{j} \right] \boldsymbol{R}_{C}^{1/2}$$

Signal time course estimation

$$\hat{\boldsymbol{b}}_{S}(t) = \boldsymbol{R}_{C}^{1/2} \left[ \sum_{j=1}^{Q} (\boldsymbol{\gamma}_{j} - 1) \boldsymbol{u}_{j} \right] \boldsymbol{R}_{C}^{-1/2} \boldsymbol{b}_{C}(t)$$

Prewhitening beamforming

$$\hat{s}_{PW}(\boldsymbol{r},t) = \frac{\boldsymbol{l}^{T}(\boldsymbol{r})(\hat{\boldsymbol{R}}_{S} + \boldsymbol{\mu}\boldsymbol{I})^{-1}\hat{\boldsymbol{b}}_{S}(t)}{\boldsymbol{l}^{T}(\boldsymbol{r})(\hat{\boldsymbol{R}}_{S} + \boldsymbol{\mu}\boldsymbol{I})^{-1}\boldsymbol{l}(\boldsymbol{r})}$$

# Partitioned factor analysis (PFA) Variational Bayesian Factor Analysis (VBFA) Data model:

measured data 
$$\rightarrow y_n = Ax_n + v_n$$
  
 $\nearrow \uparrow \uparrow \checkmark$  sensor noise  
mixing matrix factors  
**Prier probability:**

$$p(\boldsymbol{x}_n) = N(\boldsymbol{x}_n \mid 0, \boldsymbol{I}) \qquad p(\boldsymbol{A}) = \prod_{m,l}^{M,L} N(A_{m,l} \mid 0, \lambda_m \boldsymbol{\alpha}_l)$$
$$p(\boldsymbol{v}_n) = N(\boldsymbol{v}_n \mid 0, \boldsymbol{\Lambda})$$

**Derivation of posterior probability:** 

 $p(\boldsymbol{A} \mid \boldsymbol{y}) = \operatorname*{arg\,max}_{q(\boldsymbol{A} \mid \boldsymbol{y})} F(q), \quad p(\boldsymbol{x} \mid \boldsymbol{y}) = \operatorname*{arg\,max}_{q(\boldsymbol{x} \mid \boldsymbol{y})} F(q)$ 

Here  $F(q) = \int d\mathbf{x} d\mathbf{A} [\log p(\mathbf{x}, \mathbf{y}, \mathbf{A}) - \log q(\mathbf{x} | \mathbf{y}) - \log q(\mathbf{A} | \mathbf{y})]$ 

### Variational Bayes EM algorithm

E step:  $p(\mathbf{x} | \mathbf{y}) = \underset{q(\mathbf{x}|\mathbf{y})}{\operatorname{arg\,max}} F(q)$ 

$$\boldsymbol{\Gamma} = \overline{\boldsymbol{A}}^T \boldsymbol{\Lambda} \overline{\boldsymbol{A}} + M \boldsymbol{\Psi}^{-1} + \boldsymbol{I}$$
  
for  $p(\boldsymbol{x}_n \mid \boldsymbol{y}_n) = N(\boldsymbol{x}_n \mid \overline{\boldsymbol{x}}_n, \boldsymbol{\Gamma})$   
 $\overline{\boldsymbol{x}}_n = \boldsymbol{\Gamma}^{-1} \overline{\boldsymbol{A}}^T \boldsymbol{\Lambda} \boldsymbol{y}_n$ 

M step:  $p(A | y) = \underset{q(A|y)}{\operatorname{arg\,max}} F(q)$ 

$$\overline{\boldsymbol{A}} = \boldsymbol{R}_{yx} (\boldsymbol{R}_{xx} + \boldsymbol{\alpha})^{-1}$$
  
for  $p(\boldsymbol{A} \mid \boldsymbol{y}_n) = \prod_{m,l}^{M,L} N(\boldsymbol{a}_m \mid \overline{\boldsymbol{a}}_m, \lambda_m \boldsymbol{\Psi})$   
 $\boldsymbol{\Psi} = \boldsymbol{R}_{xx} + \boldsymbol{\alpha}$ 

$$\boldsymbol{\alpha} = \underset{\boldsymbol{\alpha}}{\operatorname{arg\,min}} F(q) \implies \boldsymbol{\alpha} = \frac{1}{M} \operatorname{diag}(\bar{\boldsymbol{A}}^T \boldsymbol{\Lambda} \bar{\boldsymbol{A}} + \boldsymbol{\Psi}^{-1})$$
$$\boldsymbol{\Lambda} = \underset{\boldsymbol{\Lambda}}{\operatorname{arg\,min}} F(q) \implies \boldsymbol{\Lambda} = \frac{1}{N} \operatorname{diag}(\boldsymbol{R}_{yy} - \bar{\boldsymbol{A}} \boldsymbol{R}_{yx}^T)$$

# **Partitioned factor analysis (PFA)**

Stimulus-Evoked Factor Analysis (SEFA)
Data model

Control:  $y_n = Bu_n + v_n$ Task:  $y_n = Ax_n + Bu_n + v_n$ 

(1) Apply VBFA to control data and obtain  $\overline{B}$ , and the noise precision A. (2) Apply VBFA to task data, and obtain  $\hat{b}_{s}(t) = E_{A}E_{x}[Ax_{n}] = \overline{A}\overline{x}_{n}$ 

 $\hat{\boldsymbol{R}}_{S} = E_{A} E_{\boldsymbol{x}} [(\boldsymbol{A} \boldsymbol{x}_{n}) (\boldsymbol{A} \boldsymbol{x}_{n})^{T}] = \overline{\boldsymbol{A}} \boldsymbol{R}_{xx} \overline{\boldsymbol{A}}^{T} + \boldsymbol{\Lambda}^{-1} \operatorname{tr} [\boldsymbol{R}_{xx} (\boldsymbol{R}_{xx} + \boldsymbol{\alpha})^{-1}]$ 

(3) Use these estimated results for adaptive beamforming.

 $\hat{s}_{PFA}(\boldsymbol{r},t) = \frac{\boldsymbol{l}^{T}(\boldsymbol{r})\hat{\boldsymbol{R}}_{S}^{-1}\hat{\boldsymbol{b}}_{S}(t)}{\boldsymbol{l}^{T}(\boldsymbol{r})\hat{\boldsymbol{R}}_{S}^{-1}\boldsymbol{l}(\boldsymbol{r})}$ 

For details, visit poster P-116, (session P3-1) 8/21 10:00—12:00PM



### Data without background sources



### Data with background sources





 $\downarrow$ 







## Computer Simulation: Robustness to insufficient control data



Tc:400 time points







**PFA** 





y (cm)





## Auditory evoked field



### Non-ideal scenarios for two-condition measurements

# Some target sources are also active in the control condition Task: $\boldsymbol{b}(t) = \boldsymbol{b}_{S}(t) + \boldsymbol{b}_{I}(t) + \boldsymbol{n}(t)$ Control: $\boldsymbol{b}_{C}(t) = \boldsymbol{b}_{S}(t)' + \boldsymbol{b}_{I}(t) + \boldsymbol{n}(t)$

Some sources are active only in the control condition

Task:  $\boldsymbol{b}(t) = \boldsymbol{b}_{S}(t) + \boldsymbol{b}_{I}(t) + \boldsymbol{n}(t)$ Control:  $\boldsymbol{b}_{C}(t) = \boldsymbol{b}_{I}(t) + \boldsymbol{n}(t) + \boldsymbol{b}_{A}(t)$ 

These additional terms may affect the performance of PFA

Prewhitening technique is robust in these scenarios, as discussed at poster P-163, (session P4-1) 8/22 3:00—5:00PM

### **Computer simulation for non-ideal scenarios**



**Relative source intensity** 

	control	task
First source	1	1.5
Second source	1.5	1.5
Third source	1	1.5



96 paired data sets generated

#### Signal-to-Interference Ratio:0.5







#### Signal-to-Interference Ratio:0.25













#### Signal-to-Interference Ratio:0.33

#### **Relative source intensity**

	control	task
First source	1.5	1
Second source	1.5	1.5
Third source	1	1.5





PFA





# Summary

•We propose two methods to obtain source reconstruction robust to the existence of large background brain activity.

- 1) Prewhitening beamforming
- 2) Partitioned factor analysis + adaptive beamforming

•Both methods are effective in ideal two-condition measurements.

•Partitioned factor analysis is very robust to a case where the number of time samples is small.

•Both methods are significantly robust to non-ideal scenarios of twocondition experiments. However, prewhitening method gives smaller source estimation bias than the PFA method.

Thank you for your attention